

## Mounting:



## Mounting with spacer bar:

Distance

Sensor 1

Example: The 5 holes in the setup display correspond to the number of holes between the sensors, plus the mounting hole.

Sensor 2

# Mounting without spacer bar:

The displayed value is the distance between the inner transducer fronts.



Position the sensors according to the number of holes displayed. Apply coupling paste (Magnalube) to the sensors. Mount the transducers on a horizontal pipeline between two and four o'clock (see picture on the left)

# deltawaveC-P Quickstart



## Signals: The following graphs may be displayed in the oscilloscope window



The image in the middle shows a relatively poor signal-to-noise ratio, but a correct measurement in this case is still possible. If you do not have a valid signal check if you have used enough Magnalube, if the BNC cables are connected correctly, and if the deltawaveC-P is parameterised properly. Execute sensor test (see below) to test complete signal chain.



Time:15:22:45	AUTOWINDOW: OFF	
Re <mark>un Num: O</mark>		Flow 1
Vs 2215.0m/s	T1 22.0°C STAT	US: VS ERR
SigQ 100	T2 20.4°C	

 $\rightarrow$  Check or move the signal in the OSC

 $\rightarrow$  Perform the Quick Setup again

 $\rightarrow$  Check parameters and correct if necessary

#### VS ERR:

The above error message appears in the measuring window if the current measured speed of sound deviates by more than 20% from the parameterised speed of sound. In the example (see picture above), water 20°C was parameterised (ca. 1486 m/s), the measured sound velocity deviates by more than 20% (green frame), so that "VS ERR" is displayed in the status line. Possible reasons:

- 1. Wrong signal (W instead of V, V instead of Z)
- 2. Medium not correct / unknown
- 3. After performing a sensor test

### Sensor test:

- 1. Open oscilloscope window, AUTOWINDOW must be off
- 2. Reduce the delay to 0 µs via arrow buttons
- 3. Instead of the speed of sound "SENSORTEST" is now displayed
- 4. Connect both sensors and apply some coupling gel
- 5. Hold the transducers as shown on the right (slightly offset!)
- 6. The sensors are working correctly, if after a short zero line received signals are visible (see picture left)



Picture left:Test ok, there are no signals at the beginning of the time framePicture middle:Test not ok, here the sensors are not connected, signals arrive at the beginningPicture right:Test not ok, converter connected, but no acoustic contactNote:The signal illustration may vary depending on the sending code and sensor type